

UNIVERSITÄT KAISERSLAUTERN

A CONSTRUCTION OF \mathbb{Q} -GORENSTEIN
SMOOTHINGS OF INDEX TWO

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Preprint No 203



FACHBEREICH MATHEMATIK

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by Theo de Jong and Duco van Straten.

Introduction.

The notion of \mathbb{Q} -Gorenstein smoothings has been introduced by Kollár. ([Ko], 6.2.3). This notion is essential for formulating Kollár's conjectures on smoothing components for rational surface singularities. He conjectures, loosely speaking, that every smoothing of a rational surface singularity can be obtained by blowing down a deformation of a partial resolution, this partial resolution having the property (among others) that the singularities occurring on it all have \mathbb{Q} G-smoothings. (For more details and precise statements see [Ko], ch. 6.) It is therefore of interest to construct singularities having \mathbb{Q} G-smoothings. Let us recall the definition:

Definition [Ko]: Let X be a reduced surface singularity with $X - \{x\}$ \mathbb{Q} -Gorenstein. Let $X_T \rightarrow T$ be a one parameter smoothing. The smoothing is called \mathbb{Q} -Gorenstein (\mathbb{Q} G for short) if some multiple of the canonical class of X_T is Cartier. X is called a \mathbb{Q} G-singularity if there exists a \mathbb{Q} G-smoothing of X .

The smallest natural number k such that k times the canonical class is Cartier is called the index. It is proved in [Ko] 6.2.4 that the index of X_T for a \mathbb{Q} G-smoothing of X is the same as the index of X . It should be remarked here that a \mathbb{Q} G-singularity can have more than one "essentially different" \mathbb{Q} G-smoothings. This will follow from our construction, but there is also an unpublished example of Wahl.

In this paper we construct \mathbb{Q} G-singularities of index two. The construction is motivated by a paper of Jan Stevens [St] in which he proves Kollár's conjectures for rational singularities of multiplicity four.

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§ 1. Singularities of index two.

Definition 1.1 ([Wa]): A one parameter deformation $X_T \longrightarrow T$ of a (germ of a) Cohen-Macaulay space X is called ω^* -constant if the natural restriction map

$$\omega_{X_T}^* \otimes \mathcal{O}_X \longrightarrow \omega_X^*$$

is surjective (and hence an isomorphism).

Our construction of qG-singularities of index two is based on the following:

Lemma 1.2 : Let $X_T \longrightarrow T$ be a one parameter ω^* -constant smoothing of a normal surface singularity X . If X is of index two, then the smoothing is Q-Gorenstein.

proof : We have to extend an isomorphism

$$\mathcal{O}_X \rightarrow \omega_X^{[2]}$$

to the relative situation. Tensoring this with ω_X^* and taking reflexive hull this can be translated to lifting an isomorphism

$$\varphi : \omega_X^* \rightarrow \omega_X$$

to an isomorphism over T . The ω^* -constancy gives us an exact sequence

$$0 \longrightarrow \omega_{X_T}^* \xrightarrow{.t} \omega_{X_T}^* \longrightarrow \omega_X^* \longrightarrow 0$$

and it follows that the depth of $\omega_{X_T}^*$ is three, so $\text{Ext}^1(\omega_{X_T}^*, \omega_{X_T}) = 0$. From this fact we deduce the exact sequence

$$0 \rightarrow \text{Hom}(\omega_{X_T}^*, \omega_{X_T}) \rightarrow \text{Hom}(\omega_{X_T}^*, \omega_{X_T}) \rightarrow \text{Hom}(\omega_X^*, \omega_X) \rightarrow 0$$

Hence we can lift φ to a map $\varphi_T : \omega_{X_T}^* \rightarrow \omega_{X_T}$. Let K resp. C be the kernel resp. the cokernel of φ_T . Because φ is an isomorphism one deduces from the snake lemma that $K \xrightarrow{.t} K$ and $C \xrightarrow{.t} C$ are both isomorphisms. So by Nakayama K and C are zero, and therefore φ_T is an isomorphism. \square

We recall some results from [J-S2], which are essential for the rest of this article. Consider the following situation:

X : a (multi-) germ of a Cohen Macaulay surface singularity.

Y : the image of X under a generically 1-1 map to \mathbb{C}^3 .

$I_Y = \text{Hom}(\mathcal{O}_X, \mathcal{O}_Y) \subset \mathcal{O}_Y \subset \mathcal{O}_X$, the conductor.

Σ : the subvariety of Y defined by I_Y . We assume Σ to be *reduced*.

I : the ideal in $\mathcal{O}_{\mathbb{C}^3}$ of Σ .

Δ : the subvariety of X defined by I_Y .

It is proved in [J-S2] that under these circumstances one has

$\mathcal{O}_X = \text{Hom}_Y(I_Y, I_Y)$, so $X \rightarrow Y$ is determined by the pair $\Sigma \hookrightarrow Y$.

Introduced in [J-S1] is the functor of admissible deformations $\text{Def}(\Sigma, Y)$

and in [J-S2] it is proved that there is a natural equivalence between

$\text{Def}(\Sigma, Y)$ and $\text{Def}(X \rightarrow Y)$. In particular any deformation of $X \rightarrow Y$

induces a deformation of Σ .

A geometric interpretation of the ω^* -constant condition is given in the following theorem, which is [J-S2], theorem (2.1).

Proposition 2.1: Let $X_T \rightarrow Y_T$ be a one parameter deformation of $X \rightarrow Y$ over T , and $\Sigma_T \rightarrow T$ the induced one parameter deformation of Σ . Then:

$$\dim(\text{Cok}(\omega_{X_T}^* \otimes \mathcal{O}_X \rightarrow \omega_X^*)) = \dim(\text{Cok}(\mathcal{J}I_T / I_T^2 \otimes \mathcal{O}_\Sigma \rightarrow \mathcal{J}I / I^2))$$

Here $\mathcal{J}I = \{f \in I : \mathcal{J}(f) \subset I\}$ and $\mathcal{J}I_T$ is defined similarly.

In particular, a deformation of X is ω^* -constant if the induced deformation of the curve is " $\mathcal{J}I/I^2$ -constant". We remark that if X is Gorenstein and we have a so-called disentanglement of Y , (see [J-S3]), then $\dim(\mathcal{J}I/I^2)$ equals the number of triple points. ([M-P], [J-S2], 2.2).

Corollary 2.2: A rational surface singularity of multiplicity four and index two is a qG-singularity.

proof: In view of lemma 1.1 it is enough to show that every rational quadruple point has an ω^* -constant smoothing. This is stated as corollary (2.5) of [J-S2], but no proof was given.

A generic projection Y of X has as reduced singular locus a curve Σ of multiplicity three and type two. \mathfrak{f}/I^2 is a cyclic module generated by the class of a certain $\Phi \in \mathfrak{f}$. Let $f = 0$ be a defining equation for Y , and let $f_t = f + t\Phi$ (t small). Then $Y_t := (f_t = 0)$ has smooth normalization. For all these facts we refer to [J-S4]. §1.

Now $\Sigma \subset Y_t$ is an admissible deformation, in which Σ is not deformed at all, so certainly \mathfrak{f}/I^2 -constant. So the induced deformation of X is a smoothing and is ω^* -constant by (2.1). \square

This corollary was proved by J. Stevens [St], who used a different method.

§ 3. *The construction.*

In this paragraph we compare surfaces which have projections as in §2 with the *same* Σ . We fix the notation in the following

Diagram 3.1

$$\begin{array}{ccc} X_1 \supset \Delta_1 & & \Delta_2 \subset X_2 \\ \downarrow & & \downarrow \\ \{f_1=0\} = Y_1 \supset \Sigma & \text{====} & \Sigma \subset Y_2 = \{f_2=0\} \end{array}$$

Furthermore, let I_k be the ideal of Σ in \mathcal{O}_{Y_k} , $k=1,2$.

Proposition 3.2 : Suppose \mathfrak{f}/I^2 is a cyclic module \mathcal{O}_Σ -module. Then there is a 1-1 correspondence between ω^* -constant smoothing components of X_1 and X_2 . Moreover, corresponding components are isomorphic up to a smooth factor.

proof: Let $f \in \mathfrak{f}I$ project onto a generator of $\mathfrak{f}I/I^2$, and let $X_{1,t}$ be an ω^* -constant smoothing of X_1 . By projection we get an admissible deformation $\Sigma_t \hookrightarrow Y_{1,t}$. We can assume that $Y_{1,t} = \{f_{1,t} = 0\}, t \neq 0$, has only pinch points and triple points, and so the deformed curve $\Sigma_t, t \neq 0$ only has triple points. By assumption, we can write $f_k = q_k \cdot f + r_k, k=1,2$, and $r_k \in I^2$. As the deformation of X_1 is ω^* -constant, the deformation of Σ is $\mathfrak{f}I/I^2$ -constant by 2.1, so we can lift f to an $f_t \in \mathfrak{f}I_t$. Now define $f_{2,t} = q_{2,t} \cdot f_t + r_{2,t}$, where $q_{2,t}$ is a generic perturbation of $q_2, r_{2,t} \in I_t^2$ is a general perturbation of r_2 and put $Y_{2,t} = \{f_{2,t} = 0\}$. Now the singular locus of $Y_{2,t}$ is Σ_t and by openness of versality we may assume that the normalization $X_{2,t}$ of $Y_{2,t}$ is smooth. By proposition 2.1 $X_{2,t}$ is an ω^* -constant smoothing of X_2 . The fact that these components are isomorphic up to a smooth factor follows from the principle of I^2 -equivalence ([J-S1], 1.16). \square

Proposition 3.3 : Suppose the ideal (f_1, f_2) defines a multiplicity four structure on Σ . Then X_1 and X_2 have index ≤ 2 .

proof : Because Y_1 and Y_2 are both singular along Σ , it follows from the assumption that the pullback of f_m on X_k vanishes with multiplicity exactly two along $\Delta_k (m \neq k)$ and nowhere else. Hence we get an isomorphism $\mathcal{O}_{X_k} \rightarrow I_k^{[2]}$, and as I_k is a canonical ideal we are done. \square

Theorem 3.4 : Suppose that (f_1, f_2) defines a multiplicity four structure on Σ and that $\mathfrak{f}I/I^2$ is a cyclic \mathcal{O}_Σ -module. Suppose that X_1 and X_2 are normal. Then there is a 1-1 correspondence between qG -components of X_1 and X_2 . Moreover, corresponding components are isomorphic up to smooth factors.

proof: Combine 3.2, 3.3, and 1.1. \square

Remark 3.5 : In case that X_1 is Gorenstein, it is proved in [M-P] that $\int I/I^2$ is a cyclic module generated by the class of f_1 . Moreover, the \mathcal{O}_{X_1} ideal I_1 is *principal*. Any $g \in I$ whose class in I_1 is a generator we call an adjoint, and the surface $\{g=0\}$ an adjoint surface of Y_1 . Now $f_2 = q.f_1 + u.g^2$, $q \in \mathcal{O}_{\mathbb{C}^3}$ and u a unit satisfies the condition of 3.3. So in this situation one can apply theorem 3.4. Remark that then qG -components of X_1 are simply smoothing components and also the condition of normality of X_1 can be dropped.

§4.

Examples.

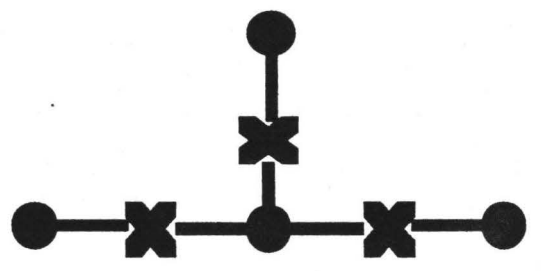
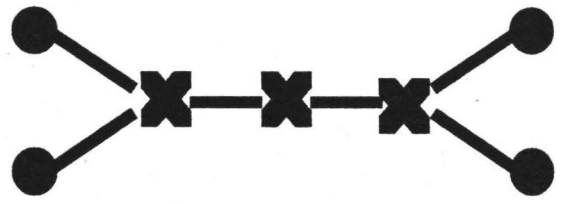
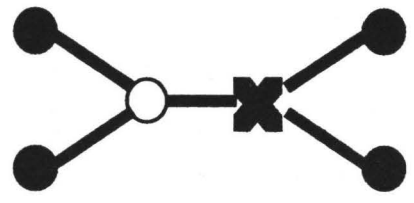
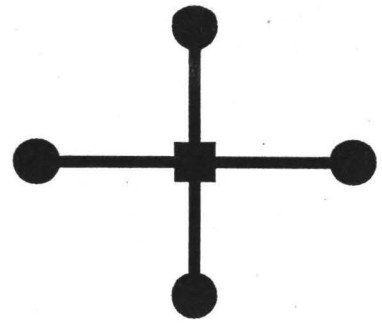
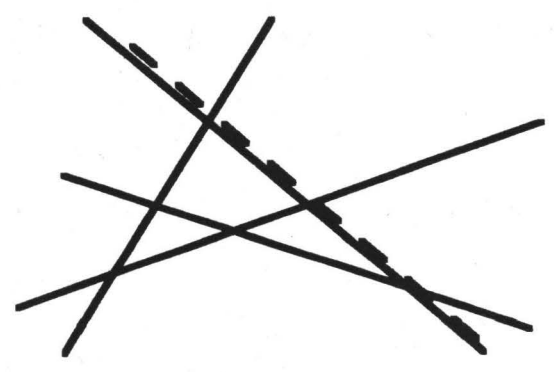
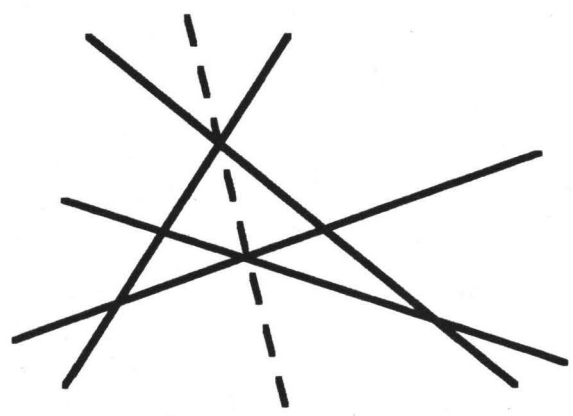
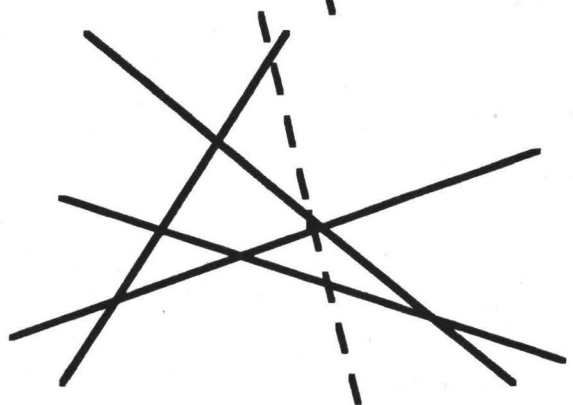
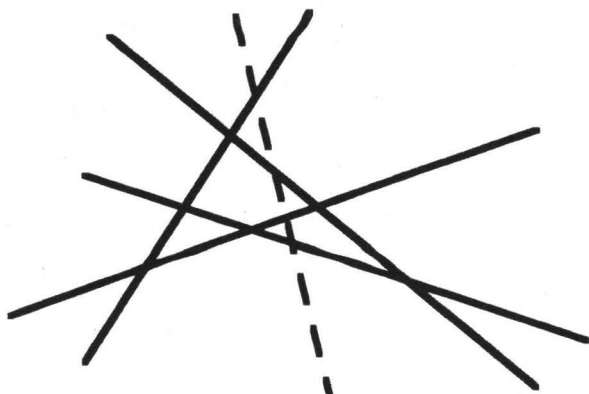
Example 4.1 : Let $f_1 = xyz$, $Y_1 = \{f_1 = 0\}$ and let $X_1 = \mathbb{C}^2 \amalg \mathbb{C}^2 \amalg \mathbb{C}^2$ be the normalization of Y_1 . Then $I = (xy, yz, zx)$. X_1 is obviously Gorenstein and $g = xy + yz + zx$ can be taken as an adjoint of Y_1 . We see that $f_2 := (xy)^2 + (yz)^2 + (zx)^2 \equiv g^2 \pmod{(f_1)}$, so we can apply theorem 3.4 to conclude that the normalization X_2 of $Y_2 = \{f_2 = 0\}$ is a qG -singularity. Of course, this is well-known, as X_2 is just the cone over the rational normal curve of degree 4.

On the other hand, we can take $f_2 := (xy + yz + yx)^2 + xyz.(x^2 + y^2 + z^2) \equiv g^2 \pmod{(f_1)}$ and apply 3.4 to conclude that X_2 , which has



as dual resolution graph, is a qG -singularity.

Example 4.2 : Let $f_1 = xyz(x+y+z)$, $Y_1 = \{f_1 = 0\}$ and let $X_1 = \amalg_{i=1}^4 \mathbb{C}^2$ be the normalization of Y_1 . We consider equations of the form $f_2 = L.f_1 + r$, where r is a general element of I^2 , the corresponding $Y_2 = \{f_2 = 0\}$ and their normalizations X_2 . These X_2 now all are qG -singularities by application of 3.4. Below we give pictures of $L.f_1 = 0$ in the projective plane (the dashed line is $L=0$, the solid ones $f_1 = 0$), and the corresponding dual resolution graphs.



● = (-2) curve
 ⊠ = (-3) curve

○ = (-4) curve
 ■ = (-5) curve

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